

Second Order ODE that describes the physics: Laplace analysis of RLC electric circuit with using same values.

$$m \cdot \left(\frac{d^2}{d\tau^2} x(\tau) \right) + b \cdot \left(\frac{d}{d\tau} x(\tau) \right) + k \cdot x(\tau) = F_0 \cdot \cos(\omega_f \cdot \tau) \quad \text{Where; } A_0 = \frac{F_0}{m} \quad \text{Note; } (\omega_0)^2 = \frac{k}{m} \quad \zeta := 1 \cdot 10^0$$

Defining Inputs: $L \cdot \left(\frac{d^2}{dt^2} q(t) \right) + R \cdot \left(\frac{d}{dt} q(t) \right) + \frac{1}{C} \cdot q(t) = e(t)$

$$m := 60 \quad k := 1 \cdot 10^1 \quad \omega_0 := \sqrt{\frac{k}{m}} = 0.408 \quad b := \zeta \cdot (2 \cdot m \cdot \omega_0) = 48.99$$

$$L := m \quad C := \frac{1}{k} \quad R := b$$

$$\omega_f := \omega_0 \cdot 1.0 = 0.408 \quad A_0 := 100 \quad \text{init} := \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad b = 48.99$$

$$t1 := 0 \quad n := 10 \quad t2 := n \cdot \left(\frac{2 \cdot \pi}{\omega_f} \right) \quad \text{npoints} := 100 \cdot n = 1 \cdot 10^3 \quad \text{intvls} := \text{npoints} - 1 = 999$$

$$Fs := \left(\frac{\omega_f}{2 \cdot \pi} \right) = 0.065 \quad tmax := t2 = 153.906 \quad T := tmax = 153.906$$

$$tstep := \frac{1}{100 \cdot Fs} = 0.154 \quad d := 10\% \quad A := A_0 = 100$$

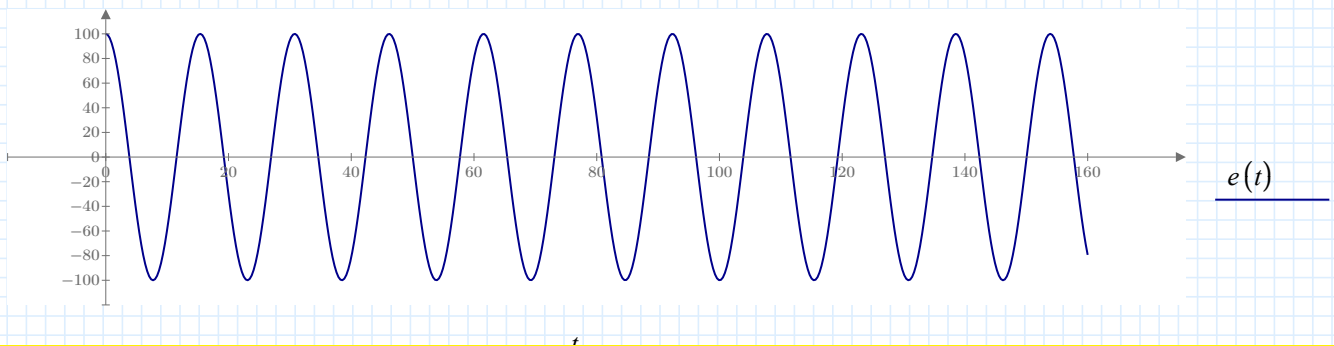
$$E_m := A \quad \omega := \omega_f = 0.408 \quad f := \frac{\omega}{2 \cdot \pi} = 0.065 \quad T := \frac{1}{f} = 15.391$$

$$u1(\tau) := A_0 \cdot \cos(\omega_f \cdot \tau) \quad e(t) := E_m \cdot \cos(\omega \cdot t) \quad T_{0.1} := \frac{T}{10} = 1.539$$

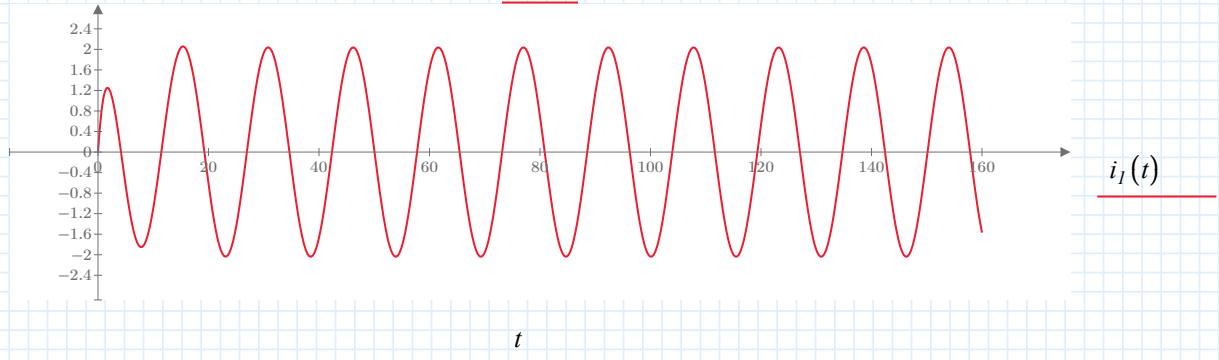
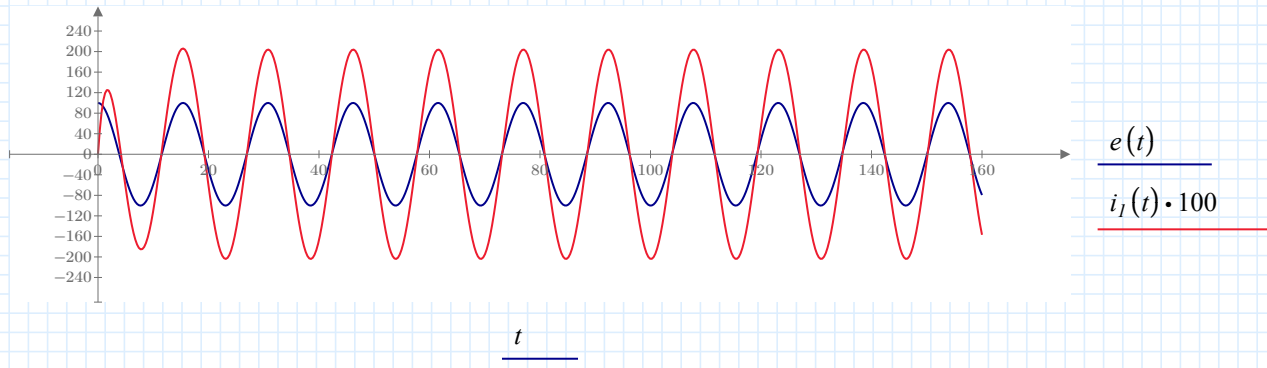
$$E_1(s) := e(t) \xrightarrow{\text{laplace}} \frac{100.0 \cdot s}{s^2 + 0.1666666666666666533}$$

$$E_1(s) := \frac{E_m \cdot s}{s^2 + \omega^2} \xrightarrow{\text{float}, 4} \frac{100.0 \cdot s}{s^2 + 0.1667}$$

$$\frac{1}{6} = 0.1666667$$



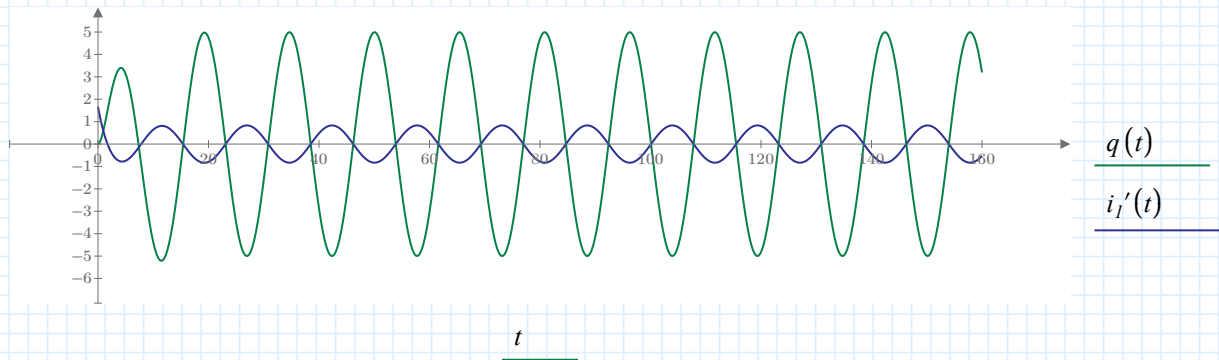
$$i_1(t) := \frac{100 \cdot s}{s^2 + \frac{1}{6}} \xrightarrow{\text{simplify}} \frac{100 \cdot s}{s^2 + \frac{1}{6}} \xrightarrow{\text{invlaplace}} \frac{100 \cdot s}{s^2 + \frac{1}{6}} \xrightarrow{\text{float}, 3} 0.325 \cdot 10^9 \cdot e^{-0.408 \cdot t} \cdot \sin(0.256 \cdot 10^{-8} \cdot t) + (2.04 \cdot \cos(0.408 \cdot t) - 2.04 \cdot \cos(0.256 \cdot 10^{-8} \cdot t)) \cdot e^{-0.408 \cdot t}$$



$$i_I(t) := 0.325 \cdot 10^9 \cdot e^{-0.408 \cdot t} \cdot \sin(0.256 \cdot 10^{-8} \cdot t) + (2.04 \cdot \cos(0.408 \cdot t) - 2.04 \cdot \cos(0.256 \cdot 10^{-8} \cdot t)) \cdot e^{-0.408 \cdot t}$$

$$q(t) := \int^t i_I(t) dt$$

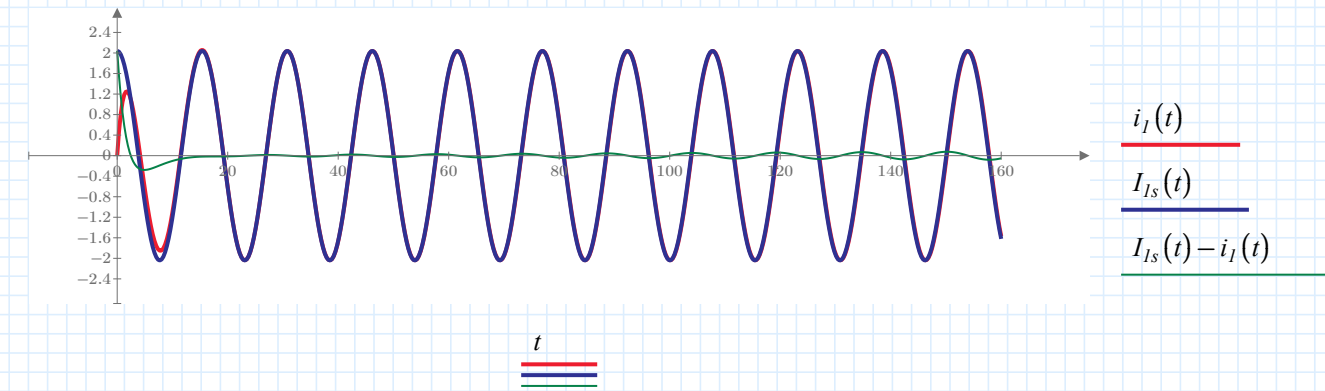
$$i_I'(t) \xrightarrow{\text{float, 3}} (-0.133 \cdot 10^9) \cdot \sin(0.256 \cdot 10^{-8} \cdot t) + 1.66 \cdot \cos(0.256 \cdot 10^{-8} \cdot t) \cdot 2.72^{-0.408 \cdot t} - 0.832 \cdot \sin(0.408 \cdot t)$$



$$Z := \sqrt{R^2 + \left(\omega \cdot L - \frac{1}{\omega \cdot C}\right)^2} = 48.99$$

$$\theta_Z := \text{atan}\left(\frac{\omega \cdot L - \frac{1}{\omega \cdot C}}{R}\right) = 0$$

$$I_{Is}(t) := \frac{E_m \cdot \cos(\omega \cdot t - \theta_Z)}{Z}$$



$$u_2(\tau) := A \cdot \left(\text{mod} \left(\tau, \frac{1}{Fs} \right) \cdot Fs \leq d \right) \cdot (\tau < tmax)$$

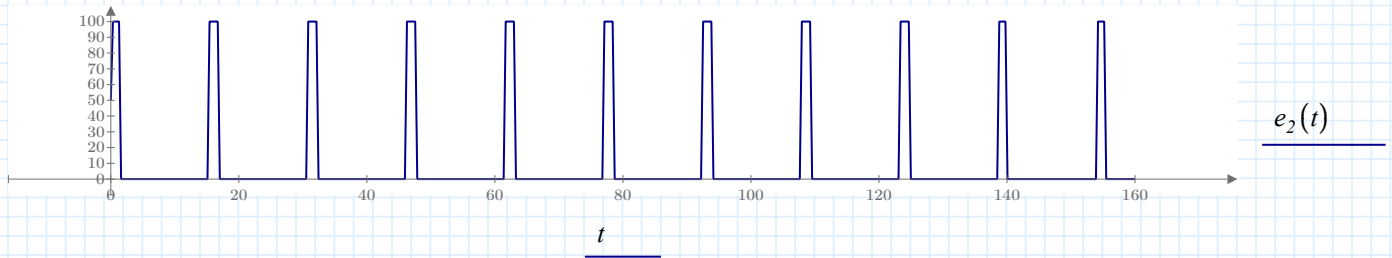
$$E_{21}(t) := E_m \cdot (\Phi(t) - \Phi(t - T_{0.1})) \xrightarrow{\text{laplace}} \frac{-100.0 \cdot e^{-1.5390597961942369 \cdot s} + 100.0}{s}$$

$$E_{21}(s) := \frac{E_m}{s} \cdot (1 - e^{-(s \cdot T_{0.1})})$$

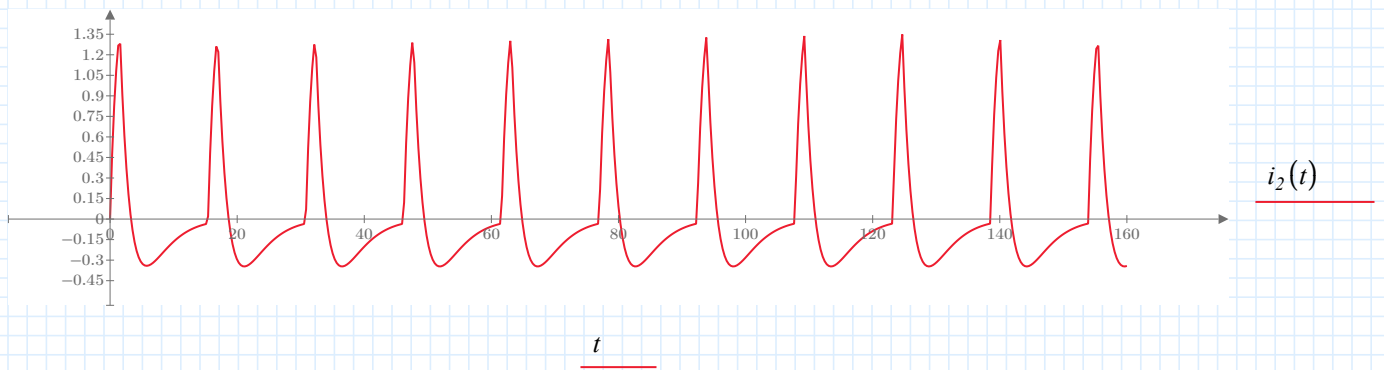
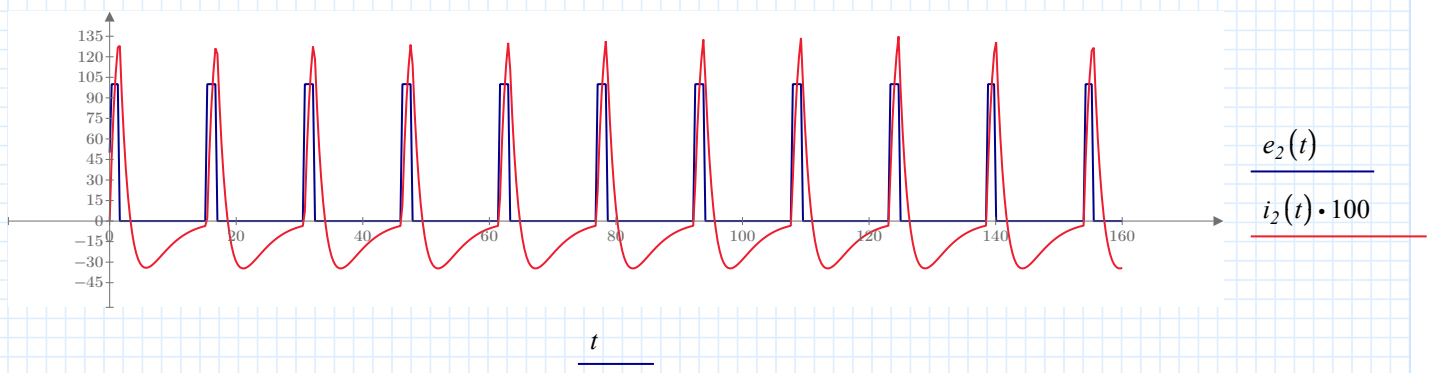
$$E_2(s) := \frac{\frac{E_m}{s} \cdot (1 - e^{-(s \cdot T_{0.1})})}{1 - e^{-s \cdot T}} \xrightarrow{\text{float, 3}} \frac{100.0 \cdot 2.72^{-1.54 \cdot s} - 100.0}{s \cdot (2.72^{-15.4 \cdot s} - 1.0)}$$

$$e_2(t) := E_m \cdot (\Phi(t) - \Phi(t - T_{0.1}))$$

$$e_2(t) := \begin{cases} \text{while } t > T \\ \quad | \quad t \leftarrow t - T \\ \text{if } t < T \\ \quad | \quad e_2(t) \end{cases}$$



$$i_2(t) := \frac{E_m \cdot (1 - e^{-1.539 \cdot s})}{s} \cdot (1 + e^{-15.39 \cdot s} + e^{-15.39 \cdot s \cdot 2} + e^{-15.39 \cdot s \cdot 3} + e^{-15.39 \cdot s \cdot 4} + e^{-15.39 \cdot s \cdot 5} + e^{-15.39 \cdot s \cdot 6} + e^{-15.39 \cdot s \cdot 7} + e^{-15.39 \cdot s \cdot 8} + e^{-15.39 \cdot s \cdot 9} + e^{-15.39 \cdot s \cdot 10}) \xrightarrow{\text{simplify invlaplace}} \frac{1}{s \cdot L + R + \frac{1}{s \cdot C}}$$



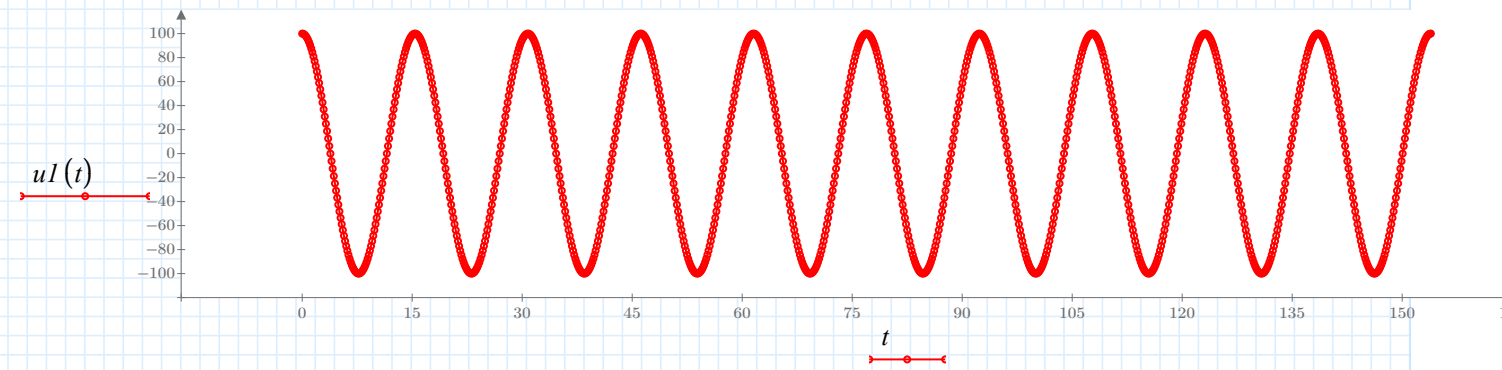
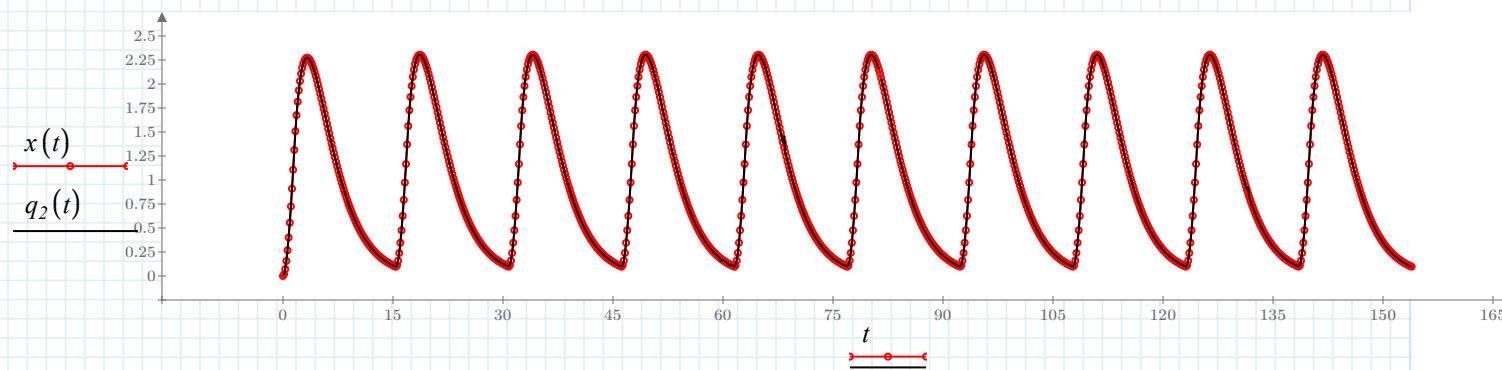
$$q_2(t) := \int_0^t i_2(t) dt$$

$i_2'(t) \rightarrow ?$



```

m * (d^2 x(tau) / d tau^2) + b * (d x(tau) / d tau) + k * x(tau) = u2(tau)
x(0) = 0      x'(0) = 0
x := Odesolve(x(tau), tmax, intvls)
t := 0, tstep .. tmax
    
```





$$v(t) := \frac{d}{dt}x(t) \quad ke(t) := .5 \cdot m \cdot v(t)^2 \quad a(t) := \frac{d^2}{dt^2}x(t)$$

