

**The Pharmacokinetics dose response with 3 compartment model:
(The data are from the EXCEL FILE delieved by Dr Zitta)**

$XY :=$

7	394.63
10	318.63
15	243.34
20	209.04
25	187.74
30	176.31
45	137.89
60	114.73
90	87.22
120	74.01
150	61.61
180	60.25

$[Xtime \ Yconcentration] := [XY^{(0)} \ XY^{(1)}]$

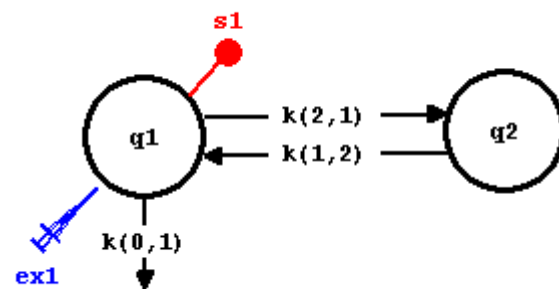


Fig1. 2-compartment model

Project parameters

Dose injection [mg] $D := 2500$

Duration_injection [min] $\tau := 3$

Initial Concentration

in Central comp't [mg/l] $c10 := 0$

in Peripheral comp't [mg/l] $c20 := 0$

Infusionrate: (for an infusion pump) $\rho := 0$

Measurement Variance: $\sigma_M := 7.8188$

Auxilliary parameters in the system

$Number_of_Artificial_Protocols := 2$

$$f(time) := \begin{cases} \frac{D}{\tau} & \text{if } 0 \leq time < \tau \\ \rho & \text{else} \end{cases}$$

TOL := 10^{-9}

$end := 500$ Integration t (in minutes)

Here the solution of the ODE is done with Laplace Transform:

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clear_sym(D)      clear_sym(time)
clear_sym(b)      clear_sym(c10)
clear_sym(b)      clear_sym(c20)

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The f(Xtime) can also be written with the Heaviside Function:

$$f(\text{time}) := \frac{D}{\tau} \cdot \Phi(\text{time}) + \left(\rho - \frac{D}{\tau}\right) \cdot \Phi(\text{time} - \tau)$$

for simplification the calculation starts for f(t) where t=τ

$$\frac{D}{\tau} \xrightarrow{\text{laplace}} \frac{D}{s \cdot \tau}$$

Here for simplification, the x1(0) = DOSE and the transformed ODE looks like this:

$$\varepsilon(s) := -(k_{01} + k_{21}) \cdot Lx1 + k_{12} \cdot Lx2 \rightarrow Lx2 \cdot k_{12} - Lx1 \cdot (k_{01} + k_{21})$$

$$\zeta(s) := k_{21} \cdot Lx1 - k_{12} \cdot Lx2 \rightarrow Lx1 \cdot k_{21} - Lx2 \cdot k_{12}$$

- **Step Two:** Apply linear property to get a system of equations for $\hat{x}(s)$ and $\hat{y}(s)$, due to $\mathcal{L}(x') = s\hat{x}(s) - x(0)$ and $\mathcal{L}(y') = s\hat{y}(s) - y(0)$,

$$s \cdot Lx - x(0) = \varepsilon(s) \rightarrow ?$$

$$(s \cdot Ly - y(0) = \zeta(s)) \rightarrow ?$$

$$s \cdot Lx1 - D = \varepsilon(s) \xrightarrow{\text{solve, Lx1}} \frac{D + Lx2 \cdot k_{12}}{s + k_{01} + k_{21}}$$

$$s \cdot Lx2 - 0 = \zeta(s) \xrightarrow{\text{solve, Lx2}} \frac{Lx1 \cdot k_{21}}{s + k_{12}}$$

$$lapsys := \begin{bmatrix} s \cdot Lx1 - D = \varepsilon(s) \\ s \cdot Lx2 - 0 = \zeta(s) \end{bmatrix}$$

$$lapsys \xrightarrow{\substack{\text{solve, Lx1, Lx2} \\ \text{simplify}}} \left[\frac{D \cdot (s + k_{12})}{s^2 + s \cdot k_{01} + s \cdot k_{12} + s \cdot k_{21} + k_{01} \cdot k_{12}} \quad \frac{D \cdot k_{21}}{s^2 + s \cdot k_{01} + s \cdot k_{12} + s \cdot k_{21} + k_{01} \cdot k_{12}} \right]$$

$$sol(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, t) := lapsys \xrightarrow{\substack{\text{solve, Lx1, Lx2} \\ \text{simplify} \\ \text{invlaplace}}} \frac{D \cdot e^{-\frac{t \cdot (k_{01} + k_{12} + k_{21})}{2}} \cdot \left(\cosh\left(\frac{t \cdot \sqrt{4 \cdot \left(\frac{k_{01}}{2} + \frac{k_{12}}{2} + \frac{k_{21}}{2}\right)^2 - 4 \cdot k_{01} \cdot k_{12}}}{2}\right) \cdot \sqrt{4 \cdot \left(\frac{k_{01}}{2} + \frac{k_{12}}{2} + \frac{k_{21}}{2}\right)^2 - 4 \cdot k_{01} \cdot k_{12}} - k_{01} \cdot \sinh\left(\frac{t \cdot \sqrt{4 \cdot \left(\frac{k_{01}}{2} + \frac{k_{12}}{2} + \frac{k_{21}}{2}\right)^2 - 4 \cdot k_{01} \cdot k_{12}}}{2}\right) + k_{12} \cdot \sinh\left(\frac{t \cdot \sqrt{4 \cdot \left(\frac{k_{01}}{2} + \frac{k_{12}}{2} + \frac{k_{21}}{2}\right)^2 - 4 \cdot k_{01} \cdot k_{12}}}{2}\right)}{\sqrt{4 \cdot \left(\frac{k_{01}}{2} + \frac{k_{12}}{2} + \frac{k_{21}}{2}\right)^2 - 4 \cdot k_{01} \cdot k_{12}}}\right)}{1}$$

Project parameters

Dose injection [mg] D := 2500

Duration_injection [min] τ := 3

ρ := 0

$$\begin{bmatrix} k_{01} \\ k_{12} \\ k_{21} \\ V_1 \end{bmatrix} := \begin{bmatrix} 0.01972 \\ 0.04048 \\ 0.06134 \\ 4.28619 \end{bmatrix}$$

$$\begin{bmatrix} \text{Clearance} \\ V_1 \\ V_2 \\ t21 \end{bmatrix} := \begin{bmatrix} 84.50884 \\ 4.28619 \\ 6.49569 \\ 11.29983 \end{bmatrix}$$

c10 := 0 c20 := 0

$$sol(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, 3) = [1983.18944 \quad 385.04627]$$

$$X1(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, \text{tonne}) := sol(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, \text{tonne})^{(0)}$$

$$X2(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, \text{tonne}) := sol(V_1, k_{01}, k_{12}, k_{21}, D, \tau, \rho, c10, c20, \text{tonne})^{(1)}$$

j := 0 .. 400

Xtime2 := 0 .. 500



