

General parameters

Material:	$f_y := 235 \cdot \frac{N}{mm^2}$
Elasticity modulus:	$E := 210000 \cdot \frac{N}{mm^2}$
Shear modulus:	$G := 81000 \cdot \frac{N}{mm^2}$
ASCEM Fig 3.3:	$C_1 := 1.348$
ASCEM Fig 3.3:	$C_2 := 0.630$
Alabeo en el extremo:	$k_w := 1$
Effective length:	$k := 1$
Load-shear center distance:	$z_g := 0 \text{ mm}$
Coefficient of imperfection 1:	$\alpha_{LT} := 0.34$
Partial safety coefficient:	$\gamma_{M0} := 1.05$

$$M_{CR}(I_z, I_w, I_t, L) := C_1 \cdot \frac{\pi^2 \cdot E \cdot I_z}{(k \cdot L)^2} \left(\sqrt{\left(\frac{k}{k_w}\right)^2 \cdot \frac{I_w}{I_z} + \frac{(k \cdot L)^2 \cdot G \cdot I_t}{\pi^2 \cdot E \cdot I_z}} + (C_2 \cdot z_g)^2 - C_2 \cdot z_g \right)$$

$$\lambda_{LT}(I_z, I_w, I_t, L, W_{ply}) := \sqrt{\frac{W_{ply} \cdot f_y}{M_{CR}(I_z, I_w, I_t, L)}}$$

$$\phi_{LT}(I_z, I_w, I_t, L, W_{ply}) := 0.5 \cdot \left(1 + \alpha_{LT} \cdot (\lambda_{LT}(I_z, I_w, I_t, L, W_{ply}) - 0.2) + (\lambda_{LT}(I_z, I_w, I_t, L, W_{ply}))^2 \right)$$

or in a better way:

$$\phi_{LT}(I_z, I_w, I_t, L, W_{ply}) := \left| \frac{\lambda \leftarrow \lambda_{LT}(I_z, I_w, I_t, L, W_{ply})}{0.5 \cdot (1 + \alpha_{LT} \cdot (\lambda - 0.2) + \lambda^2)} \right|$$

$$X_{LT}(I_z, I_w, I_t, L, W_{ply}) := \frac{1}{\phi_{LT}(I_z, I_w, I_t, L, W_{ply}) + \sqrt{\phi_{LT}(I_z, I_w, I_t, L, W_{ply})^2 - \lambda_{LT}(I_z, I_w, I_t, L, W_{ply})^2}}$$

better:

$$X_{LT}(I_z, I_w, I_t, L, W_{ply}) := \left| \frac{\phi \leftarrow \phi_{LT}(I_z, I_w, I_t, L, W_{ply})}{\phi + \sqrt{\phi^2 - \lambda_{LT}(I_z, I_w, I_t, L, W_{ply})^2}} \right|$$

$$M_{Rd}(I_z, I_w, I_t, L, W_{ply}) := X_{LT}(I_z, I_w, I_t, L, W_{ply}) \frac{W_{ply} \cdot f_y}{\gamma_{M0}}$$

Profile	I_z (mm ⁴)	W_{ply} (mm ³)	I_t (mm ⁴)	I_w (mm ⁶)	L (m)	M_{sd} (kN·m)
"IPE240"	283.4·10 ⁴	73.92·10 ³	12.88·10 ⁴	37.39·10 ⁹	3.2	45
"IPE360"	1043·10 ⁴	1019·10 ³	37.32·10 ⁴	313.6·10 ⁹	6.1	135

LATERAL BUCKLING

"HEA140" 389.3·10⁴ 84.85·10³ 8.13·10⁴ 15.06·10⁹ 4.7 52.1

"HEB240" 3923·10⁴ 498.4·10³ 102.7·10⁴ 486.9·10⁹ 5.9 68.3

$$\lambda_{LT}(400 \cdot \text{cm}^4, 5 \cdot 10^4 \text{ cm}^6, 4 \text{ cm}^4, 5 \text{ m}, 100 \text{ cm}^3) = 0.594$$

$$M_{Rd}(400 \cdot \text{cm}^4, 5 \cdot 10^4 \text{ cm}^6, 4 \text{ cm}^4, 5 \text{ m}, 100 \text{ cm}^3) = 18.807 \text{ kJ}$$

Type in profile name `prof := "IPE360"`

```

idx := try
  match(prof, Profile) ORIGIN
on error
  ORIGIN

I.z := I_z_idx      W.ply := W_ply_idx
I.t := I_t_idx      I.w := I_w_idx
L. := L_idx

ProfileName := Profile_idx

X.LT := lambda_LT(I.z, I.w, I.t, L., W.ply)
lambda.LT := lambda_LT(I.z, I.w, I.t, L., W.ply)
phi.LT := phi_LT(I.z, I.w, I.t, L., W.ply)

```

ProfileName = "IPE360" I.z = (1.043·10⁷) mm⁴ W.ply = (1.019·10⁶) mm³

I.t = (3.732·10⁵) mm⁴ I.w = (3.136·10¹¹) mm⁶ L. = 6.1 m

`lambda.LT = 1.033`

`phi.LT = 1.033`

`X.LT = 1.033`

$$\overrightarrow{\lambda_{LT}(I_z, I_w, I_t, L, W_{ply})} = \begin{bmatrix} 0.356 \\ 1.033 \\ 0.523 \\ 0.412 \end{bmatrix}$$

$$\overrightarrow{M_{Rd}(I_z, I_w, I_t, L, W_{ply})} = \begin{bmatrix} 15.603 \\ 131.41 \\ 16.594 \\ 102.766 \end{bmatrix} \text{ kJ}$$

$$\overrightarrow{\phi_{LT}(I_z, I_w, I_t, L, W_{ply})} = \begin{bmatrix} 0.59 \\ 1.175 \\ 0.692 \\ 0.621 \end{bmatrix}$$

$$\overrightarrow{X_{LT}(I_z, I_w, I_t, L, W_{ply})} = \begin{bmatrix} 0.943 \\ 0.576 \\ 0.874 \\ 0.921 \end{bmatrix}$$

Vectorization ist done to be on the safe side but would only be necessary for M_{Rd} here.