

$$T_P := 10.4 \text{ s}$$

$$H_s := 4.3 \text{ m}$$

$$d := 30 \text{ m}$$

$$TT := 3 \text{ hr}$$

You defined T later differently depending on  $\omega$ , so I renamed that variable which you seem to use just in the very last region

$$\delta\omega := 0.01$$

$$n := 400$$

If you really need  $\omega$  up to 40 rad/s then change to  $n := 4000$

$$\omega_p := \frac{2 \cdot \pi}{T_P} = 0.604 \frac{\text{rad}}{\text{s}}$$

$$\varphi := \frac{T_P}{\sqrt[2]{H_s}} = 5.015 \frac{\text{s}}{\text{m}^{\frac{1}{2}}}$$

$$c := \left\| \begin{array}{l} \text{if } \frac{T_P}{\sqrt[2]{H_s}} \leq 3.6 \frac{\text{s}}{\text{m}^{\frac{1}{2}}} \\ \quad \left\| \begin{array}{l} 5 \\ \text{if } 3.6 \frac{\text{s}}{\text{m}^{\frac{1}{2}}} < \frac{T_P}{\sqrt[2]{H_s}} < 5 \frac{\text{s}}{\text{m}^{\frac{1}{2}}} \\ \quad \left\| \begin{array}{l} \exp \left( 5.75 - 1.15 \cdot \frac{\sqrt[2]{m}}{\text{s}} \cdot \frac{T_P}{\sqrt[2]{H_s}} \right) \\ \text{if } \frac{T_P}{\sqrt[2]{H_s}} \geq 5 \frac{\text{s}}{\text{m}^{\frac{1}{2}}} \\ \quad \left\| 1 \end{array} \right. \end{array} \right. \\ \end{array} \right. = 1$$

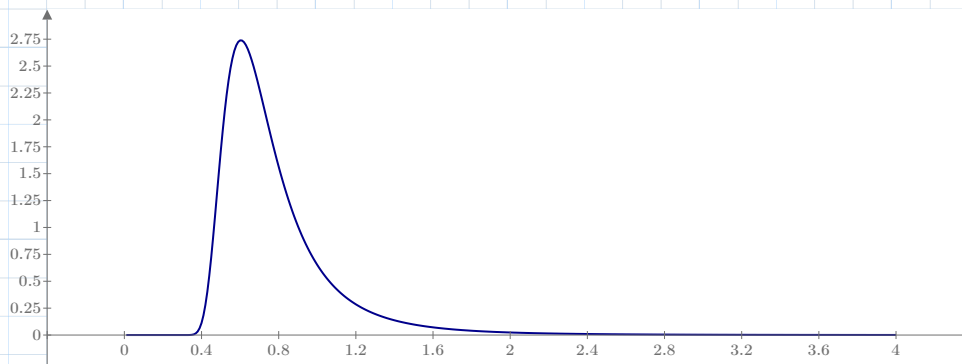
$$\sigma(\omega) := \left\| \begin{array}{l} \text{if } \omega \leq \omega_p \\ \quad \left\| 0.07 \\ \text{else} \\ \quad \left\| 0.09 \end{array} \right. \right.$$

$$\alpha := \frac{5}{16} \cdot \frac{H_s^2 \cdot \omega_p^4}{g^2} \cdot (1 - 0.278 \ln(c)) = 0.008$$

$\alpha$  is not dependent on  $\omega$  so why did you made it a function of  $\omega$  ?

$$S_{\eta}(\omega) := \alpha \cdot g^2 \cdot \omega^{-5} \cdot \exp \left( -\frac{5}{4} \left( \frac{\omega}{\omega_p} \right)^{-4} \right) \cdot c \cdot \exp \left( -0.5 \left( \frac{\omega - \omega_p}{\sigma(\omega) \cdot \omega_p} \right)^2 \right)$$

$$\omega := 0 \cdot \frac{1}{s}, \delta\omega \cdot \frac{1}{s} \dots n \cdot \delta\omega \cdot \frac{1}{s} \quad \text{range, only uses for plotting}$$



$$S_{\eta\eta}(\omega) \quad (m^2 \cdot s)$$

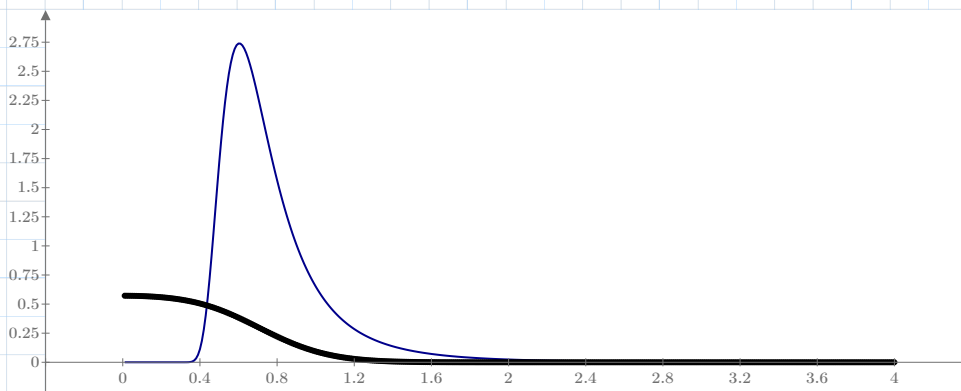
$$\omega \quad \left(\frac{1}{s}\right)$$

$$T(\omega) := \frac{2 \cdot \pi}{\omega}$$

$$L(\omega) := \frac{g \cdot (T(\omega))^2}{2 \cdot \pi} \cdot \sqrt{\tanh\left(\frac{4 \cdot \pi^2}{(T(\omega))^2} \cdot \frac{d}{g}\right)}$$

$$k(\omega) := \frac{2 \cdot \pi}{L(\omega)}$$

$$G(\omega) := \frac{\omega}{\sinh(k(\omega) \cdot d)}$$

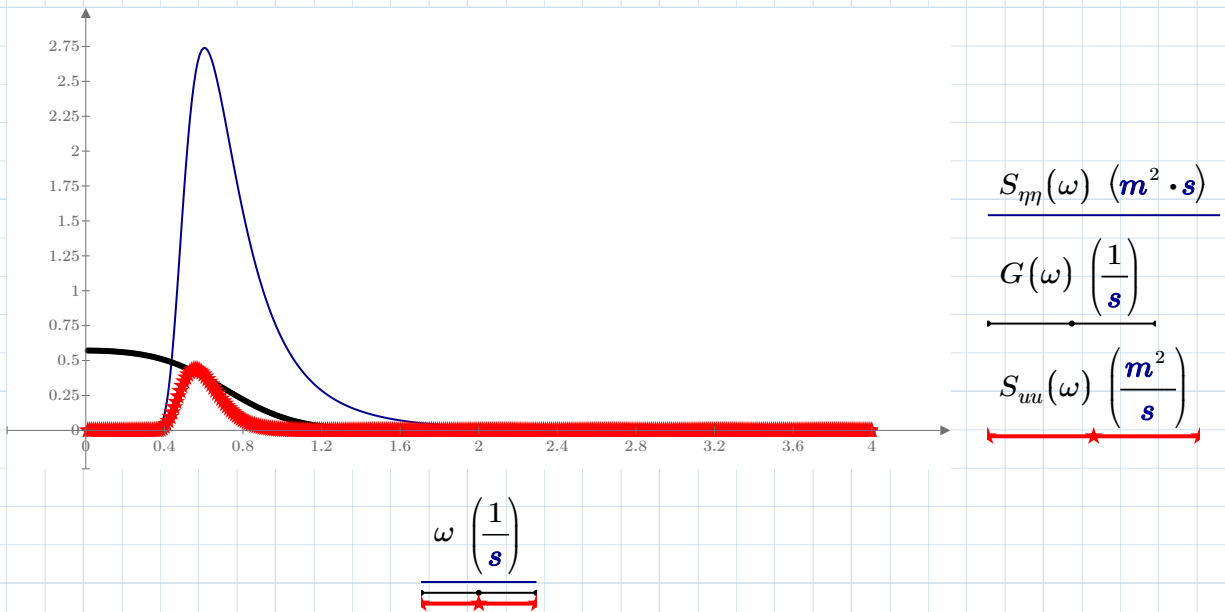


$$S_{\eta\eta}(\omega) \quad (m^2 \cdot s)$$

$$G(\omega) \quad \left(\frac{1}{s}\right)$$

$$\omega \quad \left(\frac{1}{s}\right)$$

$$S_{uu}(\omega) := (G(\omega))^2 \cdot S_{\eta\eta}(\omega)$$



$$M_0 := \int_0^{\frac{2}{s}} \omega^0 \cdot S_{uu}(\omega) d\omega$$

$$M_0 = 0.11 \frac{m^2}{s^2}$$

$$M_1 := \int_0^{\frac{2}{s}} \omega^1 \cdot S_{uu}(\omega) d\omega$$

$$M_1 = 0.066 \frac{m^2}{s^3}$$

$$M_2 := \int_0^{\frac{2}{s}} \omega^2 \cdot S_{uu}(\omega) d\omega$$

$$M_2 = 0.041 \frac{m^2}{s^4}$$

$$U_s := \sqrt[2]{M_0}$$

$$U_s = 0.332 \frac{m}{s}$$

$$T_u := 2 \cdot \pi \cdot \sqrt[2]{\frac{M_0}{M_2}}$$

$$T_u = 10.229 s$$

$$\tau := \frac{TT}{T_u}$$

$$\tau = 1.056 \cdot 10^3$$

Not sure if this is what you had in mind - I used the variable TT which you defined at the beginning as T in your sheet